

Math 010 Exam 3
Spring 2026

For full credit: Please show work using techniques from this course and use correct mathematical notation.

1. (6 pts) Let $V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x, y \in \mathbb{R} \right\}$ with usual addition, but scalar multiplication defined by $c \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ cy \end{bmatrix}$.

Though several vector space axioms hold, this is not a vector space. Show that one of the following axioms fails.

7. $k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$
8. $(k + m)\mathbf{u} = k\mathbf{u} + m\mathbf{u}$
9. $k(m\mathbf{u}) = (km)(\mathbf{u})$

$$\text{Let } \vec{u} = \begin{bmatrix} x \\ y \end{bmatrix}.$$

$$\#8 \text{ LHS: } (k+m)\vec{u} = \begin{bmatrix} x \\ (k+m)y \end{bmatrix} = \begin{bmatrix} x \\ km+ym \end{bmatrix}$$

$$\begin{aligned} \text{RHS: } k\vec{u} + m\vec{u} &= k \begin{bmatrix} x \\ y \end{bmatrix} + m \begin{bmatrix} x \\ y \end{bmatrix} \\ &= \begin{bmatrix} x \\ ky \end{bmatrix} + \begin{bmatrix} x \\ my \end{bmatrix} = \begin{bmatrix} 2x \\ ky+my \end{bmatrix} \end{aligned}$$

Since $\begin{bmatrix} x \\ ky+my \end{bmatrix} \neq \begin{bmatrix} 2x \\ ky+my \end{bmatrix}$ for all x ,

that is, $\text{LHS} \neq \text{RHS}$, axiom 8 fails.

2. (6 pts) Use the Subspace Test to determine whether

$$W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x + y - z = 0 \right\}$$

is a subspace of \mathbb{R}^3 .

Let $\vec{u} = (u_1, u_2, u_3)$ and $\vec{v} = (v_1, v_2, v_3)$
be in W . $\vec{u} + \vec{v} = (u_1 + v_1, u_2 + v_2, u_3 + v_3)$.

$$\begin{aligned} & (u_1 + v_1) + (u_2 + v_2) - (u_3 + v_3) \\ &= u_1 + u_2 - u_3 + v_1 + v_2 - v_3 \\ &= 0 + 0 \quad \text{since } \vec{u}, \vec{v} \in W. \\ &= 0. \quad \text{Thus } \vec{u} + \vec{v} \in W. \end{aligned}$$

Let k be any scalar.

$$k\vec{u} = (ku_1, ku_2, ku_3)$$

$$\begin{aligned} ku_1 + ku_2 - ku_3 &= k(u_1 + u_2 - u_3) \\ &= k(0) = 0 \end{aligned}$$

$$k\vec{u} \in W.$$

W is a subspace.

3. (6 pts) Determine whether

$$\begin{matrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \\ \left\{ \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 5 \end{bmatrix} \right\} \end{matrix}$$

is linearly independent. If it is dependent, express one vector as a linear combination of the other two.

$$\begin{bmatrix} 2 & 2 & 3 \\ 0 & 1 & 2 \\ 2 & 3 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & -1 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

Since row reducing produces a row of zeros, the set is dependent.

To find a linear combination, find rref.

$$\begin{matrix} \vec{c}_1 & \vec{c}_2 & \vec{c}_3 \\ \begin{bmatrix} 2 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1/2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \end{matrix}$$

Since $\vec{c}_3 = -\frac{1}{2}\vec{c}_1 + 2\vec{c}_2$, we have

$$\vec{v}_3 = -\frac{1}{2}\vec{v}_1 + 2\vec{v}_2.$$

4. a. (4 pts) Show that the given set is a basis for \mathbb{R}^2 .

$$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$$

$$\begin{vmatrix} 1 & 1 \\ 1 & -1 \end{vmatrix} = -1 - 1 = -2 \neq 0.$$

Thus the set is a basis for \mathbb{R}^2 .

OR $\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$

Since this reduces to the identity, the set is a basis.

- b. (2 pts) Answer without performing any computations: Is it possible that the given set is a basis for \mathbb{R}^3 ? Briefly explain why or why not.

$$\left\{ \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ 4 \\ -1 \end{bmatrix} \right\}$$

No. A basis for \mathbb{R}^3 has 3

vectors. This set cannot span

\mathbb{R}^3 .

5. (6 pts) Determine whether each statement is true or false. Justify briefly.

a. If A and B are row equivalent matrices, they have the same column space.

False. Row operations do not preserve column space. (They preserve row space.)

b. If a set contains the zero vector, then it is linearly dependent.

True. This is because the coefficient of $\vec{0}$ in a linear combination can be nonzero, but the result of the linear combination can still be zero.

c. The intersection of two subspaces of a vector space is always a subspace.

True. We proved a theorem similar to this in class.

6. (8 pts) Find a basis for the subspace of \mathbb{R}^3 spanned by

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

State the dimension of the subspace.

$$\begin{bmatrix} 1 & 2 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & -1 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Since columns 1 and 2 are pivot columns, the basis is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix} \right\}$ with dimension 2.

7. (10 pts) Let $B = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ and let S denote the standard basis.

a. Find $P_{B \rightarrow S}$.

$$\left[\begin{array}{cc|cc} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 1 \end{array} \right] \text{ shows that } P_{B \rightarrow S} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$

b. Find $[\mathbf{v}]_B$ for $\mathbf{v} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$.

$$\begin{aligned} \left[\begin{array}{cc|c} 2 & 1 & 5 \\ 1 & 1 & 3 \end{array} \right] &\rightarrow \left[\begin{array}{cc|c} 2 & 1 & 5 \\ 0 & -1 & -1 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 2 & 0 & 4 \\ 0 & 1 & 1 \end{array} \right] \\ &\rightarrow \left[\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 1 \end{array} \right] \quad [\vec{v}]_B = \begin{bmatrix} 2 \\ 1 \end{bmatrix}. \end{aligned}$$

c. Use the matrix you found in part (a) to compute $[\mathbf{v}]_S$. Briefly comment on this result.

$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \end{bmatrix} = [\vec{v}]_S.$$

This is \vec{v} , since S is the standard basis for \mathbb{R}^2 . It verifies that $P_{B \rightarrow S}$ is correct.

8. (8 pts) Let

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 1 & 2 & 2 \end{bmatrix}.$$

Find:

a. a basis for $\text{null}(A)$

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & -1 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$x_1 = 2x_3$, $x_2 = -2x_3$. Let $x_3 = t$.

$\vec{x} = \begin{bmatrix} 2t \\ -2t \\ t \end{bmatrix}$, so the basis is $\left\{ \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} \right\}$.

b. $\text{rank}(A)$

2 (the number of leading 1s)

c. $\text{nullity}(A)$

1 (the dimension of the null space)

9. (8 pts) Prove **one** of the following.

a. If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$ is a basis for a vector space V , then every vector \mathbf{v} in V can be expressed in the form $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_r\mathbf{v}_r$ in exactly one way.

b. If $\{\mathbf{v}_1, \mathbf{v}_2\}$ is linearly independent and \mathbf{v}_3 does not lie in $\text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$, then $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent.

a. Let $\vec{v} \in V$. Then since S spans V , there are c_i such that

$$\vec{v} = c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n. \text{ Suppose}$$

there are k_i such that

$$\vec{v} = k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_n\vec{v}_n. \text{ Then}$$

$$\begin{aligned} \vec{v} - \vec{v} = \vec{0} &= (c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n) \\ &\quad - (k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_n\vec{v}_n) \end{aligned}$$

$$\Rightarrow (c_1 - k_1)\vec{v}_1 + (c_2 - k_2)\vec{v}_2 + \dots + (c_n - k_n)\vec{v}_n = \vec{0}$$

Since S is linearly independent,

$c_i = k_i$ for all i . Thus the representation is unique.

b. Suppose $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$.

If $c_3 \neq 0$, then $\vec{v}_3 = -\frac{c_1}{c_3} \vec{v}_1 - \frac{c_2}{c_3} \vec{v}_2$,

Contradicting that $\vec{v}_3 \notin \text{span} \{ \vec{v}_1, \vec{v}_2 \}$.

If $c_3 = 0$, then $c_1 \vec{v}_1 + c_2 \vec{v}_2 = \vec{0}$

so $c_1 = c_2 = 0$ because $\{ \vec{v}_1, \vec{v}_2 \}$ is

an independent set. Thus $c_1 = c_2 = c_3 = 0$,

so $\{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$ is a linearly

independent set.